CAPITAL STRUCTURE AND INVESTMENT DYNAMICS WITH FIRE SALES

Douglas Gale and Piero Gottardi
European University Institute
Department of Economics

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EUI Working Paper ECO 2013/09
Abstract

We study a general equilibrium model in which firms choose their capital structure optimally, trading off the tax advantages of debt against the risk of costly default. The costs of default are endogenous: bankrupt firms are forced to liquidate their assets, resulting in a fire sale if there is insufficient liquidity in the market. When the corporate income tax rate is zero, the optimal capital structure is indeterminate, there are no fire sales, and the equilibrium is Pareto efficient. When the tax rate is positive, the optimal capital structure is uniquely determined, default occurs with positive probability, firms’ assets are liquidated at fire-sale prices, and the equilibrium is constrained inefficient. More precisely, firms’ investment is too low and, although the capital structure is chosen optimally, in equilibrium too little debt is used. We also show that introducing more liquidity into the system can be counter-productive: although it reduces the severity of fire sales, it also reduces welfare.

JEL Nos: D5, D6, G32, G33

Keywords: Debt, equity, capital structure, default, market liquidity, constrained inefficient, incomplete markets

1 Introduction

The financial crisis of 2007-2008 and the current sovereign debt crisis in Europe have focused attention on the macroeconomic consequences of debt financing. In this paper, we turn our attention to the use of debt finance in the corporate sector and study the general-equilibrium effects of debt finance on investment and growth. More precisely, we show that there is underinvestment in equilibrium when markets are incomplete and firms use debt and equity to finance investment.

At the heart of our analysis is the determination of the firm’s capital structure. In the classical model of Modigliani and Miller (1958), capital structure is indeterminate. To obtain a determinate capital structure, subsequent authors appealed to market frictions, such
as distortionary taxes, bankruptcy costs, and agency costs. We follow this tradition and assume the optimal capital structure balances the tax advantages of debt against the risk of costly bankruptcy. Debt has a tax advantage because interest is not subject to the corporate income tax. Bankruptcy is perceived as costly because it forces the firm to sell assets at fire-sale prices. The firm will balance the perceived costs of debt and equity in choosing its capital structure and we will see that these two costs support an interior optimum for the capital structure.

In our model, both the corporate income tax and the cost of bankruptcy represent a pure redistribution of resources rather than a burden on consumers. The corporate income tax revenue is returned to consumers in the form of lump sum transfers. Similarly, bankruptcy results in a fire sale of assets, but this is a transfer of value from creditors to the shareholders of the solvent firms that buy the assets. Moreover, we consider an environment with a representative consumer, so that a redistribution of resources has no effect on welfare. Nonetheless, a rational, value-maximizing manager of a competitive firm will perceive the tax as a cost of using equity finance and the risk of a fire sale in bankruptcy as a cost of using debt. These perceived costs act like a tax on capital and distort the investment decision.

The economy We assume that time is discrete and the horizon is infinite. There are two commodities at each date, a perishable consumption good and a durable capital good. The economy consists of two productive sectors, one for each commodity. The consumption good is the sole input for the production of capital goods, which is subject to decreasing returns to scale. Capital goods are the sole input for the production of consumption goods, which is subject to constant returns to scale.

Production of the capital good is instantaneous, so firms in the capital-producing sector choose inputs and outputs to maximize profits at each date. The profits are distributed to consumers. The consumption producing sector, by contrast, requires long-lived capital as an input. To finance the purchase of capital, firms issue debt and equity. Constant returns to scale ensure that interest, dividends and retained earnings as well as corporate tax payments exhaust the firm’s revenue in each period. Production and the capital structure of a firm are chosen by its manager so as to maximize the firm’s market value, which is the sum of the market value of the debt and equity outstanding.

The representative consumer maximizes the discounted sum of lifetime utilities. He decides how much of his income to consume or save at each date, using savings to purchase debt and equity issued by firms, and receives the dividends and interest payments on the securities purchased in the past.

Bankruptcy In order to allow for the possibility of bankruptcy, we assume that the production of consumption goods is subject to productivity shocks in the form of stochastic depreciation of capital. Of course, default and bankruptcy are only possible if the firm issues

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a positive amount of debt. We follow Gale and Gottardi (2011) in modeling the bankruptcy process as an extensive-form game consisting of three stages: renegotiation, liquidation and settlement. A firm in distress first attempts to restructure its debt by making an offer to exchange new debt and equity claims for the old debt. If the attempt to renegotiate the debt fails, i.e., the creditors reject the firm’s offer, then and only then will the firm be forced to liquidate its assets. The firm’s assets are sold on a competitive capital market and the liquidated value is paid to the creditors in the settlement stage.

There always exists a sub-game perfect equilibrium of the renegotiation game in which all creditors reject the firm’s offer and renegotiation fails. To eliminate such trivial failures of the bankruptcy process, we consider here the case where renegotiation succeeds if and only if there exists a sub-game perfect equilibrium in which a feasible offer is accepted. With this qualification, the bankruptcy process has a unique sub-game perfect equilibrium in which the firm fails to renegotiate its debt if and only if the present value of the liquidated assets is less than the face value of the debt. In other words, the debt can be rolled over unless the firm is insolvent in this sense.

Bankruptcy procedures have numerous flaws (see Bebchuk, 1988; Aghion, Hart and Moore, 1992; Shleifer and Vishny, 1992). In the present model, we focus on one potential source of market failure, the so-called finance constraint, which requires buyers to pay for their purchases of assets with the funds (cash) available to them, not with the issue of IOUs. Hence the potential buyer who values the assets most highly may not be able to raise enough finance to purchase the assets at their full economic value.

In our highly simplified environment, all potential buyers value the assets symmetrically, so the only friction is the finance constraint. Thus bankruptcy is “costly” only in the sense that assets sold off in an illiquid market may fetch less than full economic value: if the finance constraint is binding, the market price of the assets is determined by the amount of cash in the market, rather than by economic fundamentals. Despite this friction, bankruptcy is ex post efficient. Assets sold at fire sale prices represent a transfer of value from creditors to buyers, rather than a deadweight loss. Notice that the illiquidity of the asset market and the cost of bankruptcy are endogenously determined in equilibrium. If there is enough liquidity, there will be no loss from fire sales.

**Capital structure** As a baseline, we use the “frictionless” case in which the corporate income tax rate is zero. In that case,

i. The competitive equilibrium allocation is Pareto efficient and maximizes the utility of the representative agent subject to the resource feasibility constraints.

ii. The equilibrium capital structure of firms is indeterminate, subject only to the constraint that the amount of debt must be small enough that there is no risk of costly bankruptcy.

With a zero corporate income tax rate, the finance constraint never “binds” and bankruptcy is not “costly.” When the corporate income tax rate is positive, we get quite different results.
i’. Equilibrium is constrained inefficient.

ii’. The optimal capital structure is uniquely determined in equilibrium and firms are financed by positive amounts of risky debt and equity.

iii’. Each firm faces a positive probability of bankruptcy and bankruptcy is costly in the sense that the liquidated value of the firm is less than its fundamental or economic value as a going concern.

It is interesting that the introduction of a single friction (the positive corporate tax rate) changes so many features of the equilibrium. The intuition for point iii’ is simple. If debt were not risky (the probability of bankruptcy equaled zero) or bankruptcy were not costly (bankrupt firms could be liquidated with no loss of value), then firms would use 100% debt finance to avoid the corporate income tax. But, in equilibrium, 100% debt finance is inconsistent with both a zero probability of bankruptcy and no fire sales for bankrupt assets. A similar argument establishes point ii’. If firms used 100% equity finance, there would be no bankruptcy and hence no fire sales. But this means that a single firm could issue a small amount of debt at no cost in terms of bankruptcy and benefit from the tax hedge. The uniqueness of the capital structure follows from the fact that a rational manager will equate the marginal costs of debt and equity financing in equilibrium and, under reasonable conditions, the marginal costs are increasing.

Constrained inefficiency The main contribution of the paper is the analysis of welfare in the presence of distortions. The equilibrium is not just Pareto inefficient when the tax rate is positive (point i’. above); more interestingly, it is also constrained inefficient. We conduct two experiments to illustrate the scope for welfare-improving interventions. First, we consider a policy of controlling the level of investment. An increase in investment relative to its equilibrium level increases welfare by bringing the capital stock closer to the first best. Second, we consider a policy of controlling the probability of bankruptcy by manipulating the capital structure. Modifying the capital structure so as to increase the probability of bankruptcy above its equilibrium level increases welfare by increasing investment, which again brings the capital stock closer to the first best level. Thus, contrary to what one might expect, there is not too much instability, but too little, in equilibrium. This seems to contradict the common intuition that firms have an incentive to use too much debt financing because of the tax deductibility of interest.

The fact that there is too little bankruptcy risk and, presumably, too little debt, is surprising. There are two distortions in the model, one working to increase debt finance (the tax advantage) and the other working to reduce it (the risk of costly bankruptcy). It seems that the distortion could go either way, too much or too little debt. Nonetheless, given a fixed distortion in the form of the corporation tax rate, the optimal intervention is to increase the risk of bankruptcy. At the very least, this should give us pause when evaluating claims that less debt finance is a “good thing.”
To get some intuition for this, notice that, from the point of view of the firm, the impact of these two distortions or costs (as they are perceived by the firm), appears to be asymmetric. A solvent firm makes capital gains when it buys up the assets of liquidated firms at a fire sale price. Hence, in equilibrium, the losses made by firms when they are insolvent are offset by the capital gains earned in the states where they are solvent. In fact, as we shall see, the value of the firm in steady state is not affected by the severity of the fire sales. The corporate income tax, on the other hand, does affect the value of the firm: the revenue is recycled to the consumers, who also happen to be shareholders of the firm, but does not appear on the firm’s income and loss statement. Thus, in equilibrium, it is only the tax that depresses the value of the firm below its first-best value and causes underinvestment. Indeed, increasing the ratio of debt to equity so that the firm approaches 100% debt finance, one can approximate the first best in the limit, even if that means that default becomes more likely for each firm and the fire sales become more extreme.

**Inefficient provision of liquidity** One limitation of the basic model considered is that the only source of liquidity, of “cash” in the market for liquidated assets, is the output of the consumption good by solvent firms. It might be thought that introducing assets that are liquid, but yield lower returns, and allowing firms to accumulate them would relax the finance constraint and reduce the inefficiency associated with the cost of default. In fact, we show that the inefficiency of the equilibrium may increase.

More specifically, we introduce an alternative technology that produces the consumption good using the capital good. This technology also exhibits constant returns to scale but has a deterministic depreciation rate (equal to the expected depreciation rate of the risky technology) and a lower productivity. We show that it is never optimal for a firm to combine the two technologies: a firm either invests all its capital in the safe technology or invests all its capital in the risky technology. Provided the productivity of the safe technology is not too low, both technologies are used in equilibrium and earn the same return on capital: firms operating the safe technology make capital gains in the fire sales that compensate for the lower productivity of their capital.

The presence of firms using the safe technology increases the liquidity available in the market, which raises the liquidation price of capital. This in turn induces firms adopting the risky technology to issue more debt, so that fire sales remain an equilibrium phenomenon. Moreover, the presence of safe firms divert capital gains from solvent risky firms, thus reducing the return on capital for the latter firms. The fact that safe firms have a lower productivity of capital entails a real cost for the economy. However, increased liquidity in the system causes risky firms to issue more debt, which, as we saw, is beneficial for welfare.

Hence, when the productivity of the safe technology is not too low, so that it is used in equilibrium, but still sufficiently lower than that of the risky technology, the first effect prevails and everyone is worse off in equilibrium when the safe technology is introduced. There is thus too much liquidity rather than too little. In contrast, when the productivity of the safe technology is close to that of the risky one, introducing this technology is beneficial as it yields an allocation close to the Pareto efficient one. Thus, we get the interesting
feature that equilibrium welfare is non monotonic in the level of the productivity of the safe technology.

**Properties of equilibria** In the environment considered, we are able to characterize the steady-state equilibrium of the model, demonstrate its existence and uniqueness, and establish some comparative static properties.

We also study the non-steady-state behavior of the model in the special case where the representative consumer is risk neutral. We show that the equilibrium probability of bankruptcy, the price of capital, the fundamental value of capital and the level of investment are always equal to their steady-state values. The only variable that moves outside of the steady state is the capital stock, which converges to its steady-state value. Thus, at least in this special case, the globally stable steady state uniquely characterizes the equilibrium level of all variables other than the capital stock.

### 1.1 Related literature

In a representative agent economy without distortions, competitive equilibrium is efficient because the agent’s decision problem is identical to the planner’s problem. In the presence of distortionary taxes, the situation is very different: there may exist multiple, Pareto-inefficient equilibria (Foster and Sonnenschein, 1970). Here we find a unique Pareto-inefficient equilibrium in spite of the presence of a representative consumer. Although consumers collectively own all the assets, individual managers’ decisions are distorted by the presence of taxes and bankruptcy costs. Thus, even though tax revenues are returned to consumers and consumers end up holding the same assets after liquidation, the distortion of investment decisions imposes a welfare cost on the economy. Gale and Gottardi (2011) found similar results in a static model in which all investment was 100% debt financed.

The classical literature on the firm’s investment decision excludes external finance constraints and bankruptcy costs and uses adjustment costs to explain the reliance of investment on Tobin’s $Q$ (see Eberly, Rebelo and Vincent, 2008, for a contemporary example). The new wave literature on investment, exemplified by Sundaresan and Wang (2006) and Bolton, Chen and Wang (2009), incorporates frictions of various types, such as agency costs and distress costs of debt. Hackbarth and Maurer (2012) investigate the interaction of financing and investment in a model where there are multiple debt issues with possibly different seniority. These papers study an individual firm in partial equilibrium, rather than a large number of firms in general equilibrium.

Gomes and Schmid (2010) study a “tractable general equilibrium model with heterogeneous firms making optimal investment and financing decisions.” Kuehn and Schmid (2011) allow for endogenous assets in a structural model of default to account for credit risk. Miao and Wang (2010) develop a DSGE model of default and credit risk and calibrate it to match the persistence and volatility of output growth as well as credit spreads. All of these models assume a representative consumer and a continuum of heterogeneous firms and use computational methods to derive the equilibrium properties of the model. We endogenize the cost
of bankruptcy through the finance constraint in the market for liquidated assets, whereas these papers take the cost of bankruptcy as exogenous.

The interaction between illiquidity and incompleteness of asset markets is also studied in the literature on banking and financial crises. For models of fire sales and their impact on bank portfolios, see Allen and Gale (2004a, 2004b).

The rest of the paper is organized as follows. In Section 2 we describe the primitives of the model and characterize the first-best allocation that would be implemented by a planner seeking to maximize the welfare of the representative agent. In Section 3 we describe the firms, markets and other institutions of the economy. Section 4 contains a reduced-form description of equilibrium. Section 4.1 contains the characterization of steady-state equilibrium, shows that it existence and uniqueness and provides some comparative static results. Section 5 contains an analysis of non-steady-state paths. Section 6 shows that the first best can be achieved when there is no tax on equity and then investigates the constrained inefficiency of equilibrium. This section also contains an extension of the model to allow for a safe technology and shows that its introduction may be welfare decreasing. A brief conclusion follows. All proofs are collected in the appendix.

2 The Economy

We consider an infinite horizon production economy. Time is described by a countable sequence of dates, \( t = 0, 1, \ldots \). At each date there are two goods, a perishable consumption good and a durable capital good.

2.1 Consumers

There is a unit mass of identical, infinitely-lived consumers. The consumption stream of the representative consumer is denoted by \( c = (c_0, c_1, \ldots) \geq 0 \), where \( c_t \) is the amount of the consumption good consumed at date \( t \). For any \( c \geq 0 \), the representative consumer’s utility is denoted by \( U(c) \) and given by

\[
U(c) = \sum_{t=0}^{\infty} \delta^t u(c_t),
\]

where \( 0 < \delta < 1 \) and \( u : \mathbb{R}_+ \to \mathbb{R} \) has the usual properties: it is \( C^2 \) and such that \( u'(c) > 0 \) and \( u''(c) < 0 \) for any \( c \geq 0 \).

2.2 Production

There are two production sectors in the economy. In one, capital is produced using the consumption good as an input. In the other, the consumption good is produced using the capital good as an input.
**Capital goods sector** There is a unit mass of firms operating the technology for producing capital, given by a decreasing-returns-to-scale production function. If \( I_t \geq 0 \) is the amount of the consumption good used as an input at date \( t \), the output is \( \varphi (I_t) \geq 0 \) units of capital at the end of the period, where \( \varphi (.) \) is a \( C^2 \) function that satisfies \( \varphi' (I_t) > 0 \) and \( \varphi'' (I_t) < 0 \), for any \( I_t \geq 0 \), as well as the following Inada conditions: \( \lim_{t \to 0} \varphi' (I) = \infty \) and \( \lim_{t \to \infty} \varphi' (I) = 0 \).

**Consumption goods sector** The technology for producing the consumption good exhibits constant returns to scale. Each unit of capital used as an input at the beginning of date \( t \) produces (instantaneously) \( A > 0 \) units of output. Production in this sector is undertaken by a large number of firms which differ for the fact that the capital good depreciates with stochastic depreciation rates: the depreciation rates are assumed to be i.i.d. across firms with mean \( 1 - \bar{\theta} \). For the purpose of characterizing the efficient allocation, we can ignore therefore the heterogeneity and assume the average depreciation is deterministic, so for every unit of capital used in production at the beginning of date \( t \), \( \bar{\theta} \) units remain after production is completed.

### 2.3 Feasible allocations

At date 0, there is an initial stock of capital goods \( \bar{k}_0 > 0 \). A (symmetric) allocation is given by a sequence \( \{c_t, k_t, I_t\}^\infty_{t=0} \) that specifies the consumption \( c_t \), capital \( k_t \), and investment \( I_t \) at each date \( t \). The allocation \( \{c_t, k_t, I_t\}^\infty_{t=0} \) is feasible if, for every date \( t = 0, 1, ... \), it satisfies non-negativity,

\[
(c_t, k_t, I_t) \geq 0, \tag{2}
\]

attainability for the consumption good,

\[
c_t + I_t \leq Ak_t, \tag{3}
\]

and the law of motion for capital,

\[
k_{t+1} = \bar{\theta} k_t + \varphi (I_t), \tag{4}
\]

together with the initial condition \( k_0 = \bar{k}_0 \).

It follows from the assumptions regarding the technology for producing the capital good that there exists a unique level of the capital stock, \( 0 < \hat{k} < \infty \), satisfying the condition

\[
\varphi (A\hat{k}) = (1 - \bar{\theta}) \hat{k}.
\]

That is, the capital stock \( \hat{k} \) remains constant when all the output of the consumption good is used for investment. It is then straightforward to show that \( \hat{k} \) constitutes an upper bound on the permanently feasible levels of the stock of capital.

Proposition 1 At any feasible allocation \( \{c_t, k_t, I_t\}^\infty_{t=0} \), we have \( \limsup_{t \to \infty} k_t \leq \hat{k} \).
As a corollary, \( \hat{A} \) is an upper bound on the levels of consumption and investment that can be maintained indefinitely:

\[
\limsup_{t \to \infty} c_t \leq \hat{A}, \quad \limsup_{t \to \infty} I_t \leq \hat{A}.
\]

### 2.4 Efficient allocations

A first-best, socially optimal allocation maximizes the utility of the representative consumer within the set of feasible allocations. More precisely, it is a sequence \( \{c_t, k_t, I_t\}_{t=0}^\infty \) that solves the problem of maximizing the representative consumer’s utility (1) subject to the feasibility constraints (2), (3), (4).

To characterize the properties of the first best, consider the necessary and sufficient conditions for an interior solution \((c_t^{FB}, k_t^{FB}, I_t^{FB}) \gg 0, t = 0, 1, \ldots \) of this problem, for every \( t \),

\[
\delta^t u'(c_t^{FB}) = \lambda_t,
\]

\[
\lambda_{t+1} + \mu_{t+1} \bar{\theta} = \mu_t,
\]

and

\[
\mu_t \varphi'(I_t^{FB}) = \lambda_t.
\]

for some non-negative multipliers \( \{(\lambda_t, \mu_t)\}_{t=0}^\infty \), together with the feasibility conditions (2-4) and the initial condition \( k_0 = \bar{k}_0 \). The boundedness property established above implies that the transversality condition

\[
\lim_{t \to \infty} \sum_{s=t}^\infty \delta^s u(c_s) = 0
\]

is automatically satisfied.

Much of our analysis focuses on steady states, that is on allocations such that

\[(c_t, k_t, I_t) = (c, k, I)\]

for all \( t \). It is interesting to see what the above first-order conditions imply for an optimal steady state:

**Proposition 2** At an optimal steady state, the capital stock is given by

\[
k^{FB} = \frac{\varphi(I^{FB})}{1 - \bar{\theta}}, \tag{5}
\]

where \( I^* \) is determined by

\[
\frac{\delta A}{1 - \delta \bar{\theta}} = \frac{1}{\varphi'(I^{FB})}. \tag{6}
\]
Equation (6) has a natural interpretation in terms of marginal costs and benefits. The marginal revenue of a unit of capital at the end of period 0 is

\[ \frac{\delta A}{1 - \delta \theta} = \delta A + \delta^2 \bar{\theta} A + \ldots + \delta^t \bar{\theta}^{t-1} A, \]

because it produces \( \bar{\theta}^{t-1} A \) units of the consumption good at each date \( t > 0 \) and the present value of that consumption is \( \delta^t \bar{\theta}^{t-1} A \). The marginal cost of a unit of capital is \( \frac{1}{2} t \left( \frac{\delta}{\theta} \right) \) units of consumption at date 0. So optimality requires the equality of marginal cost and marginal revenue.

### 3 An incomplete markets economy

We study next competitive market equilibria, specifying the structure of markets available and analyzing the decision problem of individual firms and consumers.

#### 3.1 Firms

In the capital goods sector, since production is instantaneous and there is no capital, firms simply maximize current profits in each period.

In the consumption sector, there is a continuum of infinitely-lived firms. The capital of each firm is subject to a distinct depreciation shock \( \theta_t \), which is assumed to be i.i.d. across firms as well as over time. Hence firms, while ex ante identical, are different ex post. The random variable \( \theta_t \) has support \([0, 1]\) and a continuous p.d.f. \( f(\theta) \). We denote the c.d.f. by \( F(\theta) \). By the law of large numbers convention, there is no aggregate uncertainty and the aggregate depreciation rate is constant. The fraction of the capital stock that remains after depreciation is therefore equal to \( \bar{\theta} \), the expected value of \( \theta_t \). If the aggregate capital stock in the economy is \( k_t \geq 0 \) at the beginning of date \( t \), the total output of consumption good at \( t \) is \( A k_t \) and the total amount of capital remaining after production has taken place is \( \bar{\theta} k_t \).

The only additional condition we impose on the distribution \( F(\theta) \) is that the hazard rate \( \frac{f(\theta)}{1 - F(\theta)} \) is increasing.

Given the CRTS nature of the technology the size of individual firms as well as the mass of firms active in this sector is indeterminate. Moreover, since we allow for bankruptcy and the entry of new firms, the mass of active firms may change over time. To simplify the description of equilibrium, we will assume that a combination of entry and exit maintains the mass of firms equal to unity and that firms adjust their size so that each has the same amount of capital. Given the indeterminacy above, this is clearly without loss of generality and allows us to describe the evolution of the economy in terms of a representative firm with capital stock \( k_t \).

At the initial date \( t = 0 \), we assume that all capital is owned by firms in the consumption good sector and that each of these firms has been previously financed entirely by equity. Each consumer has an equal shareholding in each firm in the two sectors.
3.2 Renegotiation and default

In a frictionless environment, where firms have access to a complete set of contingent markets to borrow against their future income stream and hedge the idiosyncratic depreciation shocks, the first-best allocation can be decentralized, in the usual way, as a perfectly competitive equilibrium.

In what follows, we consider instead an environment with frictions, where the first best is typically not attainable. More specifically, in this environment there are no markets for contingent claims, the firms’ output is sold in spot markets for goods and firms are financed only with (short-term) debt and equity.

In the presence of uncertainty regarding the depreciation rate of the firm’s capital, debt financing gives rise to the risk of bankruptcy, which may be costly. In the event of default, in fact, firms are required to liquidate their assets by selling them to the solvent firms. These firms may be finance-constrained in equilibrium and whenever this happens there will be a fire sale, in which assets are sold for less than their full economic value.

Equity financing, in contrast, entails no bankruptcy risk. The cost of equity is that firms must pay a linear (distortionary) tax on equity’s returns. We assume for simplicity that the revenue of the tax on equity is used to make an equal lump sum transfer to all consumers.

A firm producing the consumption good must then choose each period the optimal composition between debt and equity financing of its purchases of capital, by trading off the costs and benefits of these two financial instruments. To analyze this decision formally we must first describe more in detail the structure of markets and the timing of the decisions taken within each period by firms and consumers.

Each date \( t \) is divided into three sub-periods, labeled \( A \), \( B \), and \( C \).

A. At the beginning of each period (sub-period \( A \)), the production of the consumption good occurs and the realization of the depreciation shock of each firm \( \theta_t \) is learnt. Also, the debt liabilities of each firm are due. The firm has three options: it can repay the debt, renegotiate (“roll over”) the debt, or default and declare bankruptcy. Renegotiation takes place via the game described in the next section, where the firm makes a take it or leave it offer to its bond holders and they simultaneously choose whether to accept or reject. Non defaulting firms may then distribute their earnings to equity holders or retain them to finance new purchases of capital.

B. In the intermediate sub-period (\( B \)), the market opens where bankrupt firms can sell their assets (their capital). A liquidity constraint applies, so that only agents with resources readily available, either solvent firms who retained earnings in sub-period \( A \) or consumers who received dividends in sub-period \( A \), can purchase the assets on sale. Let \( q_t \) denote the market price of the liquidated capital.

C. In the final sub-period (\( C \)), the production of capital goods occurs. The profits of the firms who operate in this sector are then distributed to the consumers who own them. In addition, debt holders of defaulting firms receive the proceeds of the liquidation sales
in sub-period B. The taxes on equity’s returns are due and the lump sum transfers to consumers are also made in this sub-period. All other markets open; spot markets, where the consumption and the capital goods are traded, at a price respectively 1 and $v_t$, as well as asset markets, where debt and equity issued by firms (both surviving and newly formed) to acquire capital are traded. The consumers buy and sell these securities in order to fund future consumption and rebalance their portfolios.

3.2.1 Sub-period A: The renegotiation game

Consider a firm with $k_t$ units of capital at the beginning of period $t$. The firm produces $Ak_t$ units of the consumption good, has outstanding debt with face value $d_t k_t$,\(^2\) and learns the realization of its depreciation shock $\theta_t$. The renegotiation process that occurs in sub-period $A$ between the firm and the creditors who purchased the firm’s bonds at $t - 1$ is represented by a two-stage game. Without loss of generality, we analyze the renegotiation game for the case where the firm has one unit of capital, i.e., $k_t = 1$.

S1 The firm makes a “take it or leave it” offer to the bond holders to rollover the debt, replacing each unit of the maturing debt with face value $d_t$ with a combination of equity and debt maturing the following period. The new face value of the debt, $d_{t+1}$, determines the firm’s capital structure since equity is just a claim to the residual value.

S2 The creditors simultaneously accept or reject the firm’s offer.

Two conditions must be satisfied in order for renegotiation to succeed. First, a majority of the creditors must accept the offer. Second, the rest of the creditors must be paid off in full. If either condition is not satisfied, the renegotiation fails and the firm is declared bankrupt. In that event, all the assets of the firm are frozen, nothing is distributed until the capital stock has been liquidated (sold in the market). After liquidation, the sale price of the liquidated assets is distributed to the bond holders in sub-period $C$. Obviously, there is nothing left for the shareholders in this case. Hence default is always involuntary: a firm acting so as to maximize its market value will always repay or roll over the debt unless it is unable to do so.

We show next that there is an equilibrium where renegotiation succeeds if and only if

$$d_t k_t \leq (A + q_t \theta_t) k_t,$$  \hspace{1cm} (7)

that is, if the value of the firm’s equity is negative when its capital is evaluated at its liquidation price $q_t$. Note that the condition is independent of $k_t$. Consider, with no loss of generality, the case of an individual creditor holding debt with face value $d_t$. If he rejects the offer and demands to be repaid immediately, he receives $d_t$ in sub-period $A$. With this payment he can purchase $\frac{d_t}{q_t}$ units of capital in sub-period $B$. If the firm manages to roll

\(^2\)Here and in what follows, it is convenient to denote by $d_t$ the face value of the debt issued per unit of capital acquired.
over the debt, it can retain $A$ and purchase $\frac{A}{q_t}$ units of capital in sub-period $B$. Then it will have $\frac{A}{q_t} + \theta_t$ units of capital at the end of the period. Therefore the most that the firm can offer the creditor is a claim to an amount of capital $\frac{A}{q_t} + \theta_t$ at the end of the period, with market value $v_t \left( \frac{A}{q_t} + \theta_t \right)$. So the firm’s offer will be accepted only if the creditor rejecting the offer ends up with no more capital than by accepting, that is,

$$\frac{d_t}{q_t} \leq \frac{A}{q_t} + \theta_t,$$

which is equivalent to (7). If (7) is satisfied, there exists a sub-game perfect equilibrium of the renegotiation game in which the entrepreneur makes an acceptable offer worth $d_t$ to the creditors and all of them accept. To see this, note first that the shareholders receive a non-negative payoff from rolling over the debt, whereas they get nothing in the event of default, and the creditors will not accept a lower offer. Second, the creditors will accept the offer of $d_t$ because they cannot get a higher payoff by deviating and rejecting it. Thus, we have the following simple result.

**Proposition 3** There exists a sub-game perfect equilibrium of the renegotiation game in which the debt is renegotiated if and only if (7) is satisfied.

Proposition 3 leaves open the possibility that renegotiation may fail even if (7) is satisfied. Indeed it is the case that if every creditor rejects the offer, it is optimal for every creditor to reject the offer because a single vote has no effect. In the sequel, we ignore this trivial coordination failure among lenders and assume that renegotiation succeeds whenever (7) is satisfied. We do this because we want to focus on non-trivial coordination failures.

### 3.2.2 Sub-period B: Liquidation

Let $z_t$ denote the break even value of $\theta_t$, implicitly defined by the following equation

$$d_t \equiv A + q_t z_t. \tag{8}$$

Thus a firm is bankrupt if and only if $\theta_t < z_t$. When all firms active at the beginning of date $t$ have the same size $(k_t)$, the supply of capital to be liquidated by bankrupt firms in sub-period $B$ is

$$\int_0^{z_t} \theta_t k_t f(\theta_t) \, d\theta_t.$$ 

It is a matter of indifference to shareholders whether solvent firms retain earnings or pay them out as dividends, since shareholders can sell shares to finance consumption and the manager operates the firm in the shareholders’ interests. There is no loss of generality, therefore, in assuming that solvent firms $(\theta_t \geq z_t)$ retain all of their earnings and have them
available to purchase capital in sub-period $B$. The amount of resources available to purchase capital in sub-period $B$ is so

\[ A \int_{z_t}^{1} k_t f (\theta_t) \, d\theta_t = A (1 - F (z_t)) k_t. \]

If $q_t$, the price of capital in sub-period $B$, is greater than $v_t$, the price of capital in sub-period $C$, no firm will buy capital at the price $q_t$ and the market cannot clear. This means that market clearing requires $q_t \leq v_t$ and

\[ q_t \int_{0}^{z_t} \theta_t k_t f (\theta_t) \, d\theta_t \leq A (1 - F (z_t)) k_t, \tag{9} \]

with (9) holding with equality if $q_t < v_t$, in which case all the available resources must be offered in exchange for liquidated capital.

### 3.2.3 Sub-period C: Settlement, investment and trades

**Capital sector decisions** The decision of the firms operating in the capital goods sector, in sub-period $C$, is simple. At any date $t$ the representative firm chooses $I_t \geq 0$ to maximize current profits, $v_t \varphi (I_t) - I_t$. Because of the concavity of the production function, a necessary and sufficient condition for the input $I_t$ to be optimal is

\[ v_t \varphi' (I_t) \leq 1, \tag{10} \]

with strict equality if $I_t > 0$.

The profits from the capital sector, $\pi_t = \sup_{I_t \geq 0} \{v_t \varphi (I_t) - I_t\}$, are paid to consumers in the same sub-period.

**Consumption sector decisions** In the consumption goods sector, the firm’s decision is more complicated because the production of consumption goods requires durable capital, which generates returns that repay the investment over time. So the firm has to issue securities to finance the purchase of capital. As we explained above, the number and size of firms in this sector are indeterminate because of constant returns to scale. We consider a symmetric equilibrium in which, at any date, a unit mass of firms are active and all of them have the same size, given by $k_t$ units of capital$^3$ at the end of date $t$.

The representative firm chooses its capital structure to maximize its market value, that is the value of the outstanding debt and the equity claims on the firm. This capital structure is summarized by the break even point $z_t$. Whenever the firm’s depreciation shock next period $\theta_t < z_t$, the firm defaults next period and its value is equal to the value of the firm’s

---

$^3$Because of the default of a fraction of the firms, the surviving firms who acquire their capital may grow in size in sub-period $B$, but are then indifferent between buying or selling capital at $v_t$ in sub-period $C$. Hence we can always consider a situation where the mass of active firms remains unchanged over time, while their size varies with $k_t$. 

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liquidated assets, \( A + q_{t+1} \theta_{t+1} \). If \( \theta_{t+1} > z_{t+1} \), the firm is solvent and can use its earnings \( A \) to purchase capital at the price \( q_{t+1} \). Then the final value of the firm is \( v_{t+1} \left( \frac{A}{q_{t+1}} + \theta_{t+1} \right) \), from which the amount due for the tax on equity’s returns must be subtracted. The corporate income tax rate is denoted by \( \tau > 0 \) and the tax base is assumed to be the value of the firm’s equity at the beginning of sub-period \( C \), whenever it is non negative.

To calculate the value of equity, we need two components. The first is the value of capital owned by the firm, \( v_t \left( \frac{A}{q_t} + \theta_t \right) \). The second is the value of the (renegotiated) debt, \( v_t \left( \frac{d_t}{q_t} \right) \). The tax base is the difference between these two values,

\[
v_t \left( \frac{A}{q_t} + \theta_t \right) - v_t \left( \frac{d_t}{q_t} \right).
\]

Hence, the tax payment due at date \( t + 1 \) is

\[
\tau \max \left\{ v_{t+1} \left( \frac{A}{q_{t+1}} + \theta_{t+1} \right) - v_{t+1} \left( \frac{d_{t+1}}{q_{t+1}} \right), 0 \right\} = \tau \max \left\{ \frac{v_{t+1}}{q_{t+1}} \left( A + q_{t+1} \theta_{t+1} - d_{t+1} \right), 0 \right\},
\]

and the expected value of the firm at date \( t + 1 \) is

\[
\int_0^{z_{t+1}} (A + q_{t+1} \theta_{t+1}) dF + \int_{z_{t+1}}^1 \left[ v_{t+1} \left( \frac{A}{q_{t+1}} + \theta_{t+1} \right) - \tau \frac{v_{t+1}}{q_{t+1}} \left( A + q_{t+1} \theta_t - d_{t+1} \right) \right] dF. \tag{11}
\]

Because there is no aggregate uncertainty and there is a continuum of firms offering debt and equity subject to idiosyncratic shocks, diversified debt and equity are risk-free and must bear the same rate of return. Denoting by \( r_t \) the risk-free interest rate between date \( t \) and \( t + 1 \), the present value of the firm at \( t \) is given by the expression in (11) divided by \( 1 + r_t \).

Hence the firm’s problem consists in the choice of its capital structure, as summarized by \( z_{t+1} \), so as to maximize the following objective function

\[
\frac{1}{1 + r_t} \left\{ \int_0^{z_{t+1}} (A + q_{t+1} \theta_{t+1}) dF + \int_{z_{t+1}}^1 \left[ v_{t+1} \left( \frac{A}{q_{t+1}} + \theta_{t+1} \right) - \tau v_{t+1} \left( \theta_{t+1} - z_{t+1} \right) \right] dF \right\} \tag{12}
\]

where we used (8) to substitute for \( d_{t+1} \). The value of the firm at an optimum is then equal to the market value of capital, \( v_t \). The solution of the firm’s problem in (12) has a fairly simple characterization:

**Proposition 4** There is a unique solution \( z_t \) for the firm’s optimal capital structure, given by \( z_{t+1} = 0 \) when \( \left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) Af(0) \geq \tau \) and by \( 0 < z_t < 1 \) satisfying

\[
\left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) (A + q_{t+1} z_{t+1}) \frac{f(z_{t+1})}{1 - F(z_{t+1})} = \tau
\]

when \( \left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) Af(0) < \tau \).
The consumption savings decision  The representative consumer has an income flow given by the initial endowment of capital $k_0$ and the payment of the profits $\pi_t$ of the firms in the capital good sector and of the lump sum transfers $T_t$ by the government at every date. Since he faces no income risk and can fully diversify, as we said, the idiosyncratic income risk of equity and corporate debt, the consumer effectively only trades each period a riskless asset. His choice problem reduces then to the maximization of the discounted stream of utility subject to the lifetime budget constraint:

$$\max \sum_{t=0}^{\infty} \delta^t u (c_t) \quad \text{s.t.} \quad c_0 + \sum_{t=1}^{\infty} p_t c_t = A k_0 + v_0 \bar{\theta} k_0 + \pi_0 + \sum_{t=1}^{\infty} p_t (T_t + \pi_t),$$

where $p_t = \prod_{s=0}^{t-1} \frac{1}{1+r_s}$ is the discount rate between date 0 and date $t$, given the access to risk free borrowing and lending each period at the rate $r_t$.\(^4\)

Market clearing  The market-clearing condition for the consumption good is

$$c_t + I_t = A k_t, \quad \text{for all } t \geq 0$$

The markets for debt and equity clear at any $t$ if the amount of wealth the households want to carry forward into the next period is equal to the value of debt and equity issued by firms in that period. We show in the appendix that the market-clearing condition for the securities markets is automatically satisfied if the market-clearing condition for the goods market (14) is satisfied. This is just an application of Walras’ law.

Finally, the market for capital clears if

$$k_{t+1} = \bar{\theta} k_t + \varphi (I_t)$$

4  Equilibrium

We are now ready to state the equations defining a competitive equilibrium in the environment described.

Definition 5  A competitive equilibrium is a sequence of values $\{(c_t, k_t, z_{t+1}^t, I_t^*, q_{t+1}^*, v_t^*, r_t^*)\}_{t=0}^{\infty}$ satisfying the following conditions:

1. Profit maximization in the capital good sector. For every date $t \geq 0$, $I_t^*$ solves:

$$v_t^* \varphi' (I_t^*) \leq 1 \quad \text{and} \quad (v_t^* \varphi' (I_t^*) - 1) I_t^* = 0.$$

---

\(^4\)The value of the initial endowment of capital $k_0$ equals the value of the output $A k_0$ produced with this capital in sub-period $A$ plus the value of the capital left after depreciation in sub-period $C$, $\bar{\theta} k_0 v_0$. Also, while producers of capital good operate and hence distribute profits in every period $t \geq 0$, the first equity issue is at the end of date 0 and hence the first tax revenue on equity earnings is at date $t = 1$. 

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2. **Optimal capital structure.** For every date \( t \geq 0 \), the capital structure \( z_{t+1}^* \) of the firms in the consumption good sector satisfies:

\[
\left( 1 - \frac{q_{t+1}^*}{v_{t+1}^*} \right) \left( A + q_{t+1}^* z_{t+1}^* \right) \frac{f \left( z_{t+1}^* \right)}{1 - F \left( z_{t+1}^* \right)} = \tau.
\]

and the present value of the firms in this sector satisfies the law of motion

\[
(1 + r_t^*) v_t^* = \left\{ \int_0^{z_{t+1}^*} \left( A + q_{t+1}^* \theta_{t+1} \right) dF + \right.
\]
\[
\left. \int_{z_{t+1}^*}^{1} \left( v_{t+1}^* \left( A + \theta_{t+1} \right) - \tau v_{t+1}^* \left( \theta_{t+1} - z_{t+1} \right) \right) dF \right\}
\]

3. **Optimal consumption.** The sequence \( \{ c_t^* \}_{t=0}^\infty \) satisfies the following first-order conditions

\[
\frac{\delta u' \left( c_t^* \right)}{u'(c_t^*)} = \frac{1}{1 + r_t^*},
\]

for every date \( t \geq 0 \), together with the budget constraint

\[
c_0^* + \sum_{t=1}^\infty \left( \prod_{s=0}^{t-1} \frac{1}{1 + r_s^*} \right) c_t^* = A k_0 + v_0^* \theta k_0 + v_0^* \varphi(I_0^*) - I_0^* +
\]
\[
\sum_{t=1}^\infty \left( \prod_{s=0}^{t-1} \frac{1}{1 + r_s^*} \right) \left( \tau k_t^* v_t^* \int_{z_t^*}^{1} \left( \theta_t - z_t^* \right) f \left( \theta_t \right) d\theta + v_t^* \varphi \left( I_t^* \right) - I_t^* \right)
\]

4. **Liquidation market clearing.** For every date \( t > 0 \), the asset market clears in sub-period \( B \):

\[
q_t^* \leq v_t^* \text{ and } q_t^* \int_0^{z_t^*} \theta_t dF \leq A \int_{z_t^*}^{1} dF, \text{ with equality if } q_t^* = v_t^*
\]

5. **Goods market clearing.** For every date \( t \geq 0 \), the goods market clears in sub-period \( C \):

\[
A k_t^* = c_t^* + I_t^*.
\]

6. **Capital market clearing.** For every date \( t \geq 0 \), the sequence \( \{ k_t^* \} \) satisfies the law of motion

\[
k_{t+1}^* = \partial k_t^* + \varphi \left( I_t^* \right)
\]

and \( k_0^* = \tilde{k}_0 \).
Condition 1 requires firms in the capital goods sector to maximize profits at every date, taking the price of capital goods \( v_t^c \) as given. Condition 2 requires firms in the consumption goods sector to choose their capital structures optimally. Here we assume that the optimal capital structure occurs at an interior solution \( 0 < z_t^* < 1 \). In fact, this is implied by Proposition 4 and the market-clearing condition for sub-period \( B \) (equation (9)). The law of motion for the value of the firm is simply the Bellman equation associated with the maximization problem in equation (12). Condition 3 requires that the consumption path solves the consumers’ maximization problem (13) at every date. Conditions 4 – 6 are the market-clearing conditions for the liquidated capital goods in sub-period \( B \) and for capital goods and consumption goods in sub-period \( C \). These conditions follow from equations (9), (15), and (14), respectively.

The equilibrium market prices of equity \( v_t^c \) and debt \( v_t^{bs} \) at any date \( t \) are readily obtained from the other equilibrium variables. The returns on diversified equity and debt are deterministic, because there is no aggregate uncertainty. The rate of return on diversified debt must be equal to the rate of return on diversified equity. Thus, \( v_t^c \) and \( v_t^{bs} \) must be such that the one-period expected returns on debt and equity are equal to the risk free rate.

Putting together the market-clearing condition (9) for liquidated capital in sub-period \( B \) with the optimality conditions for the firms in the consumption good sector (Proposition 4), we see that in equilibrium we must have an interior optimum for the firms’ capital structure, \( z_t \in (0, 1) \), and \( q_t < v_t \). Thus, default is costly and occurs with probability strictly between zero and one:

\[
0 < F(z_t) < 1.
\]

Intuitively, if default were costless firms would choose 100% debt financing, but this implies default with probability one, which is inconsistent with market clearing. Similarly, 100% equity financing implies that there is no default and hence default is costless, so firms should use 100% debt financing instead. The only remaining alternative is a mixture of debt and equity and costly default.

We also see from the previous analysis that uncertainty only affects the returns and default decisions of individual firms. All other equilibrium variables, aggregate consumption, investment and market prices are deterministic.

### 4.1 Steady-state equilibria

**Definition 6** A steady state is a competitive equilibrium \( \{(c_t^*, k_t^*, z_t^*, I_t^*, q_t^*, v_t^c, r_t^c)\}_{t=0}^{\infty} \) in which for all \( t \geq 0 \),

\[
(c_t^*, k_t^*, z_t^*, I_t^*, q_t^*, v_t^c, r_t^c) = (c^*, k^*, z^*, I^*, q^*, v^*, r^*).
\]

The conditions defining a steady state are readily obtained by substituting the stationarity restrictions into Conditions 1 – 6 of Definition 5 of a competitive equilibrium.

Our first result shows that a steady state exists and is unique. In addition, the system of conditions defining a steady state can be reduced to a system of two equations.
Proposition 7 Under the maintained assumptions, there exists a unique steady-state equilibrium, obtained as a solution of the following system of equations:

\[ q^* = \frac{A(1 - F(z^*))}{\int_0^{z^*} \theta f(\theta) d\theta}, \quad (16) \]

\[ v^* = \frac{\delta A}{1 - \delta \theta + \tau \int_{z^*}^1 (\theta - z^*) dF}, \quad (17) \]

\[ \left(1 - \frac{q^*}{v^*} \right) (A + q^* z^*) \frac{f(z^*)}{1 - F(z^*)} = \tau. \quad (18) \]

In a steady state, the risk free rate \( r^* \) is determined by the condition that the interest rate equals the subjective rate of time preference:

\[ \frac{1}{1 + r^*} = \delta. \]

Having simplified the system of equations defining a steady state, we can also identify some of its comparative static properties.

Proposition 8 (i) An increase in the tax rate \( \tau \) increases the steady value of \( z^* \) (and hence the debt-equity ratio) and reduces the one of \( q^* \), but the effect on \( v^* \) (and hence \( I^* \) and \( k^* \)) is ambiguous.

(ii) An increase in the discount factor \( \delta \) decreases the steady-state value of \( z^* \) (and hence the debt-equity ratio) and increases the one of \( q^* \) as well of \( v^* \), so that \( I^* \) and \( k^* \) increase too.

To get some intuition for these results, consider in particular the case of an increase in the tax rate \( \tau \). This increases the cost of equity financing, so that firms shift to higher debt financing, thus decreasing the liquidity available in sub-period B and hence the liquidation value of defaulting firms. While the direct effect of the higher tax rate is clearly to decrease \( v \), as we see from (17) the increase in debt financing \( (z) \) induced by the higher tax always raises \( v \), hence the ambiguity of the overall effect on \( v \).

5 Transition dynamics

The main focus of the rest of the paper will be on the welfare properties of equilibria, in particular on the efficiency of the investment and capital structure decisions of firms. To facilitate this analysis, we first complete the equilibrium analysis by studying the properties of the dynamics outside of the steady state. To make the analysis of the transitional dynamics tractable we will impose the additional assumption that consumers are risk neutral,

\[ u(c_t) = c_t, \text{ for all } c_t \geq 0. \quad (19) \]
As a consequence, the stochastic discount factor is constant and equal to $\delta$ and, hence,

$$\frac{1}{1 + r_t} = \delta,$$

for all $t,$ in any equilibrium. On the basis of assumption (19), we show in this section that the equilibrium dynamics converges monotonically to the steady state.

Under assumption (19), the equilibrium conditions outside the steady state can be reduced to a system of two equations. From the market-clearing condition in sub-period $B$ (Condition 4), we have

$$q_t = \frac{A(1 - F(z_t))}{\int_0^{z_t} \theta dF}.$$  \hfill (20)

Letting $q(z_t)$ denote the term on the right hand side of (20), we readily see that $q(z_t)$ is a continuously decreasing function of $z_t$ on the interval $[0,1]$, for all $t \geq 1$. The first-order condition for the optimal capital structure (Condition 2) can then be rewritten as

$$\left(1 - \frac{q(z_{t+1})}{v_{t+1}}\right)\left(\frac{A}{q(z_{t+1})} + z_{t+1}\right)\frac{f(z_{t+1})}{1 - F(z_{t+1})} = \tau.$$ \hfill (21)

Holding $v_{t+1}$ constant, an increase in $z_{t+1}$ increases the left hand side of (21), so the change in $v_{t+1}$ must decrease $\left(1 - \frac{q(z_{t+1})}{v_{t+1}}\right)$. In other words, an increase in $z_{t+1}$ must decrease $v_{t+1}$. This shows that, if we denote by $v(z_{t+1})$ the solution of (21) with respect to $v$, $v(z_{t+1})$ is a continuously decreasing function of $z_t$ on the interval $[0,1]$, for all $t \geq 1$. The profit-maximization condition 1. of the capital good producers,

$$v_t \varphi'(I_t) = 1,$$ \hfill (22)

implies that the investment level $I_t = I(v_t)$ is a well defined and strictly increasing function of $v_t$; hence $I(v(z_t))$ is a well defined and decreasing function of $z_t$ on the interval $[0,1]$, for all $t \geq 0$.

Substituting these functions for $I, v, q$ into the expressions specifying the law of motion of the market value of the firms in the consumption good sector (in Condition 2) \footnote{We also use (20) to simplify the expression in (23), as we did in the proof of Proposition 7.} and the capital market-clearing (Condition 6), we obtain the system of two difference equations below in $z$ and $k$:

$$v(z_t) = \delta \left[A + v(z_{t+1})\overline{\theta} - \tau v(z_{t+1})\int_{z_{t+1}}^1 (\theta - z_{t+1})dF\right]$$ \hfill (23)

$$k_{t+1} = \overline{\theta}k_t + \varphi(I(z_t)).$$ \hfill (24)

This dynamic system can be solved for the values $\{(k_t, z_t)\}_t^\infty$, subject to the initial conditions determining\footnote{The initial conditions are given by $k_1 = \overline{\theta}k_0 + \varphi(I_0)$, with $I_0$ determined by $\delta \left[A + v(z_1)\overline{\theta} - \tau q(z_1)\int_{z_1}^1 (\theta - z_1)dF\right] \varphi'(I_0) = 1$ as a function of $z_1$.} $k_1$. This sequence defines an equilibrium trajectory if it belongs to an equilibrium as defined in Definition 5.
The first of the two equations, (23), only depends on \( z_t \). Hence the dynamics for \( z_t \) is determined by that equation, and does not depend on \( k \). We show in the Appendix that the dynamics for \( z_t \) is as described in the following figure:

where the red line is the graph of the term on the right hand side of (23), and the blue line is the graph of the term on the left hand side, both regarded as functions of \( z \). The two curves intersect at the unique steady-state value \( z = z^* \). At that point the slope of the red curve is flatter than the slope of the blue curve. Also, both curves are negatively sloped. This implies that, starting at any initial point \( z_1 \neq z^* \), the trajectory \( \{z_t\} \) satisfying the difference equation must diverge away from \( z^* \). In fact, if \( z_1 > z^* \), \( z_t \) is monotonically increasing until it reaches a value, strictly smaller than one, beyond which a solution to (23) no longer exists.\(^7\) On the other hand, if \( z_1 < z^* \) both curves diverge to infinity and the dynamics is monotonically decreasing approaching zero. This is also unfeasible, since we see from (21), (20), (22) that when \( z \to 0 \), \( v \), \( q \), \( I \) and hence also \( k \) tend to infinity, which violate the boundedness property established in Proposition 1.

This shows that in any competitive equilibrium we must have \( z_t = z^* \) for all \( t \). From this it follows that prices and the investment level are constant along the equilibrium path, at the levels \( q_t = q(z^*) = q^* \), \( v_t = v(z^*) = v^* \) and \( I_t = I(z^*) = I^* \), for all \( t \), while the dynamics of the capital stock is determined by the law of motion

\[
k_{t+1} = \bar{\theta} k_t + \varphi (I^*) ,
\]

with \( k_1 \) determined by the initial conditions. Then

\[
k_{t+\tau+1} = \left( \bar{\theta} + \bar{\theta}^2 + \cdots + \bar{\theta}^\tau \right) \varphi (I^*) + \bar{\theta}^{\tau+1} k_t
\]

\[
\to \frac{\varphi (I^*)}{1 - \theta} = k^* \text{ as } \tau \to \infty.
\]

\(^7\)If \( z \to 1 \), the term on the right hand side converges to \( A \) and the one on the left hand side converges to 0. Thus for some finite value of \( t \) there is no value of \( z_{t+1} \) that satisfies the (23).
So the capital stock converges to its steady-state value. We have thus established the following:

**Proposition 9** Let \( \{(k_t, z_t)\}_{t=1}^{\infty} \) be a solution of (23), (24), satisfying \( k_0 = \bar{k}_0 \). Then \( \{(k_t, z_t)\}_{t=1}^{\infty} \) is an equilibrium trajectory only if, for all \( t \geq 1 \), \( z_t = z^* \), where \( z^* \) is the uniquely determined steady-state capital structure. Furthermore, \( k_t \) converges monotonically to its steady-state value, \( k^* \).

## 6 Welfare analysis

### 6.1 The inefficiency of equilibrium

If we compare the conditions for a Pareto efficient steady state derived in Proposition 2 with the conditions for a steady-state equilibrium derived in Section 4.1, we can say that steady-state equilibria are Pareto efficient if \( I^* = I^{FB} \), which happens when the equilibrium market value of capital is given by

\[
v^* = \frac{\delta}{1 - \delta \theta} A.
\]

From the equilibrium conditions, in particular Condition 2, it can be seen immediately that the equality above can hold only if \( \tau = 0 \). In that case, there is no cost of issuing equity and the firms in the consumption good sector will choose 100% equity finance. On the other hand, when \( \tau > 0 \), as we have been assuming, the equilibrium market value of capital \( v^* \) is strictly lower than \( \frac{\delta}{1 - \delta \theta} A \) and \( I^* \) and \( k^* \) are strictly less than the corresponding values at the first best steady state. Thus, in a steady state equilibrium, the financial frictions of incomplete markets and the perceived costs of default and equity financing, imply that firms invest a lower amount and the equilibrium stock of capital is lower than at the efficient steady state.\(^8\) Even with a representative consumer, competitive equilibria are Pareto inefficient, as we shall see next section.

### 6.2 Constrained inefficiency

It is not surprising that the equilibrium is Pareto-inefficient in the presence of distortionary taxation. A more surprising result is that, even in the presence of frictions, regulation of a single variable, while allowing other variables to reach their equilibrium levels, can lead to a welfare improvement. That is, competitive equilibria are also constrained inefficient. We

\(^8\)When the initial capital stock \( k_0 = \bar{k}^{FB} \) the unique Pareto efficient allocation of the economy is the Pareto efficient steady state. Since as we saw the equilibrium allocation is different, it is clearly Pareto inefficient. For other values of \( k_0 \) the difference between the Pareto efficient steady state and the equilibrium steady state does not immediately imply that the latter is Pareto-inefficient. For that, we would have to find a Pareto-preferred (non-steady-state) allocation consistent with the initial value of \( k_0 \). In the next section we provide examples of welfare improving changes in the allocation starting from the equilibrium steady state.
consider two possible types of interventions. In the first, we control the level of aggregate investment. In the second we control the breakeven level of debt. To make the analysis more transparent, we still focus our attention here on the case where consumers are risk neutral, that is (19) holds.

**Controlling investment** $I$. Starting in a steady-state equilibrium, we consider an increase in the investment level at some date $t$. Thus, at date $t$, $I$ is no longer determined by Condition 1 of Definition 5, but set equal to $I^* + \Delta I$. The rest of the equilibrium variables are determined by the agents’ optimizing decisions and market-clearing conditions. In particular, the output of capital goods at all subsequent dates responds to the exogenous change in investment. The law of motion of the capital stock is now

$$k_{t+1} = \hat{\theta}k^* + \varphi(I^* + \Delta I),$$

$$k_{t+i} = \hat{\theta}k_{t+i-1} + \varphi(I_{t+i-1}), \text{ for all } i > 1,$$

while the market-clearing condition in the liquidation market, the optimality condition for the firms’ capital structure and the law of motion for $v_t$ are still given by (20), (21) and (23). Similarly, at each subsequent date $t + i > t$, the level of $I$ is determined by the profit-maximization condition of the capital good producers, (22). Since equations (20), (21) and (23) are unchanged, the analysis of the transition dynamics in Section 5 still applies and implies that their solution is given by $z_{t+i} = z^*$, $v_{t+i-1} = v^*$, $q_{t+i} = q^*$, for all $t > 0$. It also follows that $I_{t+i} = I^*$ after date $t$.

The dynamics for consumption is given by the following equations:

$$c_t = Ak^* - (I^* + dI),$$

$$c_{t+1} = A(\hat{\theta}k^* + \varphi(I^* + dI)) - I^*,$$

$$c_{t+i} = A(k^* + \hat{\theta}^{-i} (\varphi(I^* + \Delta I) - \varphi(I^*)) - I^*, \text{ for all } i > 1.$$

Hence, the sign of the effect on welfare of this intervention is equal to the sign of

$$\left( -1 + \varphi'(I^*)A\delta \sum_{t=0}^{\infty} (\hat{\theta}^t) \right) \Delta I.$$

The term in brackets in this expression is strictly positive because, as we showed in the previous section, in a steady-state equilibrium we always have

$$A \frac{\delta}{1 - \delta \theta} > \frac{1}{\varphi'(I^*)} = v^*.$$

Hence, a temporary increase of investment above its equilibrium value increases welfare by bringing the stock of capital closer to its first-best level.

Notice that if we allow for repeated interventions of the kind described, setting the level of the investment $I = IFB$ at all dates $t + i$ for $i > 0$, it may be possible to attain the
Pareto-efficient steady state allocation after a transition of one period. It is in fact easy to verify, by a similar argument to the one above, that the following intervention:

\[
\text{at date } t, \text{ set } I_t \text{ such that } k^{FB} = \bar{\theta}k^* + \varphi(I_t)
\]

at all \( t + \tau, \quad \tau > 0 \), set \( I_{t+\tau} = I^{FB} \),

provided that \( Ak^* \geq I_t \), induces the following equilibrium consumption sequence:

\[
c_t = Ak^* - I_t \\
c_{t+i} = Ak^{FB} - I^{FB} = c^{FB} \text{ for all } t > 1.
\]

**Controlling the breakeven point** \( z \). Now consider an alternative intervention, consisting of a change in the capital structure of the firms producing in the consumption good sector, with all other variables determined as in equilibrium. In particular, we consider a permanent change \( \Delta z \) starting at some fixed but arbitrary date \( t + 1 \). The induced changes in the equilibrium variables \( q \) and \( v \) are obtained from the market-clearing condition in sub-period \( B \), (20), and the law of motion of \( v \), (23). After substituting the new value of \( z \), the new values of \( q \) and \( v \) are determined by

\[
A(1 - F(z^* + \Delta z)) = q_{t+i} \int_{z^* + \Delta z}^{z^*} \theta dF = q_{t+i} \left[ z^* f(z^*) + \int_{z^*}^{z^*} \theta dF \right], \quad (25)
\]

and \(^{10}\)

\[
v_{t+i} = \delta A + v_{t+i+1} \bar{\theta} - \tau v_{t+i+1} \int_{z^* + \Delta z}^{1} (\theta - z^* - \Delta z) dF, \quad (26)
\]

for all \( i > 0 \). We see from (25) that the new equilibrium value for \( q_{t+i} \) is the same for all \( i \) and from (26) we obtain a first-order difference equation in \( v \). The solution of this equation diverges monotonically since the coefficient on \( v_{t+i+1} \) has absolute value

\[
\left| \bar{\theta} - \tau \int_{z^* + \Delta z}^{1} (\theta - z^* - \Delta z) dF \right| < \max \left\{ \bar{\theta}, \tau \int_{z^* + \Delta z}^{1} (\theta - z^* - \Delta z) dF \right\}
\]

\[
\leq \max \{ \bar{\theta}, \tau \bar{\theta} \} = \bar{\theta} < 1.
\]

Hence, the only admissible solution is obtained by setting \( v_{t+i} \) equal to its steady-state value:

\[
v_{t+i} = v_{t+i+1} = v^* + \Delta v = \frac{\delta A}{1 - \delta \bar{\theta} + \delta \tau \int_{z^* + \Delta z}^{1} (\theta - z^* - \Delta z) dF}, \quad (27)
\]

\(^{9}\)We focus attention on a permanent, rather than a temporary, intervention to make the analysis simpler, but it is fairly easy to verify that the same welfare result holds in the case of a temporary intervention.

\(^{10}\)Note that expressions (25) and (26) give us the new equilibrium levels of \( q \) and \( v \) also for any discrete change \( \Delta z \), as long as we have \( v \geq q \), that is as long as \( z + \Delta z \) is not too close to 0.
The remaining equilibrium variables are determined by the optimality condition for the capital goods producers, \((22)\), and the capital market clearing condition, \((24)\), which are both unchanged. Since, by the previous argument, \(v_{t+1}\) is equal to its new steady-state equilibrium value, \(v^* + \Delta v\), we have \(I_{t+i} = I^* + \Delta I\) for all \(i > 0\), where the sign of \(\Delta I\) equals the sign of \(\Delta v\).

The effect on welfare is then determined, as in the case of the first intervention considered, by the change in \(I\) and hence in \(k\), and consumers’ welfare increases if and only if \(dI > 0\). From \((27)\) it is then easy to verify that sign \(\Delta v = \text{sign} \Delta z\), since

\[
\frac{d}{dz} \int_{z^*}^{1} (\theta - z^*) dF = - \int_{z^*}^{1} dF < 0
\]

and so, in the limit,

\[
\frac{dI}{dz} = \frac{dv}{dz} \frac{dI}{dv} = \frac{dv}{dz} \left( -\frac{\varphi''}{v \varphi} \right) > 0
\]

Hence, welfare is increased by a permanent increase in \(z\) above its steady-state equilibrium value.

When \(z\) is increased above \(z^*\), the equilibrium value of \(v\) increases, as we see from \((27)\), but the tax liability divided by \(v\), that is, \(\tau \int_{z^*}^{1} (\theta - z) dF\), decreases, as we can also see from \((27)\). In fact, it is because the tax liability falls relative to \(v\) that the value of capital increases. Firms do not choose a higher value of \(z\) in equilibrium because they are price takers and hence do not internalize the fact that, if they all increase \(z\), \(q\) decreases and \(v\) increases. They choose \(z\) to maximize \((12)\), without taking into account the effect of \(z\) on \(q\) and \(v\).

Also, both the default and tax costs ‘wash out’ in the welfare analysis, since they only entail a redistribution of wealth between debt holders, equity holders, and taxpayers. Given the homogeneity of consumers, such a redistribution has no effect on welfare. The only effect on welfare comes from the change in investment and capital. Any intervention that increases \(I\) and \(k\) is welfare improving.

The intervention acts directly on the threshold below which the firm has to default on its debt. To claim that an increase of this threshold corresponds to an increase in the debt-equity ratio, the change in the market value of debt and equity should also be taken into account, that is we should look at

\[
\frac{v^b}{v^e} = \frac{\int_0^z (A + q_{t+i} \theta) dF + \int_z^1 v_{t+i}(A + q_{t+i} + z) dF}{\int_z^1 v_{t+i}(\theta_{t+i} - z)(1 - \tau) dF}
\]

(28)

The effect of a marginal increment in \(z\), starting from \(z^*\) on the value of the debt equity ratio \(\frac{v^b}{v^e}\), is not straightforward to determine in general. We will show in what follows that, for a discrete, sufficiently large increment in \(z\) we have an unambiguous increase in the debt equity ratio \(\frac{v^b}{v^e}\).

Consider a sequence of discrete changes \(\Delta z\), such that \(z + \Delta z\) approaches 1. Along such sequence \(q\) goes to zero and we also see from \((26)\) that \(v\) approaches \(\frac{\delta A}{1 - \delta \theta}\) and hence, by
(24), \( I \) approaches \( I_{FB} \). That is, in the limit, the equilibrium corresponding to such an intervention converges to the steady-state, first-best allocation.\(^\text{11}\) Also, as \( z \to 1 \), we have

\[
\frac{v^b}{v^e} = \frac{\int_0^z (A + q_{i+1} \theta) dF + \int_z^1 \frac{v_{i+1} (A + q_{i+1} \tau) dF}{q_{i+1}}}{\int_z^1 v_{i+1} (1 - \tau) (\theta - z) dF} \to \frac{A + v A \lim_{z \to 1} \int_z^1 \frac{1}{q_{i+1}} dF}{0} = \infty
\]

Hence, we can indeed say that the debt equity ratio is increasing, at least in the limit, as a result of such intervention.\(^\text{12}\)

To gain some understanding for this result recall that, as noticed above, both the corporate income tax and the perceived cost of bankruptcy are transfers rather than deadweight costs. The revenue of the corporate income tax is paid to consumers and the fire sale losses of bankrupt firms provide capital gains for the solvent firms. When we look at the expression for the value of firms at a competitive equilibrium (see equation (17)), we see that only the tax payment appears as a “cost” that reduces the level of \( v \). This is because only the tax payments are transferred outside of the corporate sector, thus reducing the firms’ equilibrium value.

### 6.3 Liquidity provision

Fire sales are a necessary element of equilibrium, as we have shown. Equity is dominated by debt finance unless bankruptcy is perceived to be costly and, in equilibrium, both debt and equity finance must be used. One might think that speculators would have an incentive to accumulate liquidity in order to buy assets at fire sale prices, but speculation does little to restore the efficiency of equilibrium. As long as liquid assets yield a low return, speculators will not hold them unless they can expect capital gains from buying assets in the fire sale. The supply of liquidity will never be sufficient to eliminate fire sales. In fact, the presence of liquid assets can make the competitive equilibrium less efficient. As we have pointed out, the “costs” of bankruptcy are a transfer rather than a true economic cost. For the same reason, the capital gains from buying assets in fire sales are also a transfer. So holding low-yielding liquid assets in order to buy up assets in a fire sale is always inefficient. In fact, it can make everyone worse off than in an economy without liquid assets.\(^\text{13}\)

To represent the possibility of speculative arbitrage to provide liquidity in the market, we extend the analysis by introducing an additional, “safe” technology to produce the consumption good using the capital good, also subject to constant returns to scale. We assume that

\^\text{11} Note that the equilibrium condition (25) has an admissible solution for all \( z + \Delta z < 1 \), but not in the limit for \( z + \Delta z = 1 \).

\^\text{12} In contrast, we see from (11), that when firms act as price takers their optimal decision when \( q \to 0 \) is \( z \sim 0 \).

\^\text{13} Investing in a safe technology that is less productive than the risky technology is always inefficient. This does not mean, however, that introducing a safe technology cannot increase equilibrium welfare. Since the steady-state equilibrium is inefficient to begin with, introducing an inefficient technology can make everyone better off. The crucial question is how different the productivities of the two technologies are. We show in this section that if the productivity difference is sufficiently small, a steady-state equilibrium with the safe technology will be preferred to a steady-state equilibrium without it.
one unit of capital applied to this technology produces $B$ units of the good and that after depreciation the amount of capital remaining is $\theta$. The two technologies have then the same average depreciation rate but the depreciation rate of the safe technology is deterministic. We assume that $B < A$; otherwise, the safe technology would dominate the risky technology.

Each firm in the consumption good sector now faces a technology choice, in addition to the choice of its capital structure. Otherwise, the definition of a competitive equilibrium is unchanged.

To analyze the firms’ technology choice, consider a firm which has one unit of capital at date $t$. If the capital is entirely invested in the safe technology, the optimal capital structure is full debt financing, since there is no default risk in this case. At date $t + 1$ the firm produces $B$ units of goods which it retains and uses to buy $\frac{B}{q_{t+1}}$ units of capital. Then, at the end of date $t + 1$, the firm has $\frac{B}{q_{t+1}} + \bar{\theta}$ units of capital which is valued at $v_{t+1} \left( \frac{B}{q_{t+1}} + \bar{\theta} \right)$. In equilibrium, it is optimal for the firm to invest all its capital in the safe technology if and only if

$$v_t = \frac{1}{1 + r_t} v_{t+1} \left( \frac{B}{q_{t+1}} + \bar{\theta} \right).$$

(29)

In addition, the zero profit condition requires that the nominal value of debt issued by the firm fully investing in the safe technology is equal to $d_{t+1} = B + q_{t+1} \bar{\theta}$.

We establish first some properties of the equilibrium technology choice.

**Proposition 10** At a competitive equilibrium, if $v_{t+1} > q_{t+1}$ it is never optimal for a consumption good producer to use both technologies at the same time.

This proposition is the result of the non-convexity of the firm’s objective function associated with costly bankruptcy. If the firm has a positive amount of debt and a positive probability of default, the firm can increase its value by shifting all its production to the risky technology, keeping the default probability and the default cost unchanged and enjoying the higher returns of the technology, or to the safe technology which allows to avoid all the default risk and cost.

We show next that, as in the previous specification, in equilibrium we always have $v_{t+1} > q_{t+1}$. Suppose not, that is we have $v_{t+1} = q_{t+1}$. In that case there is no default cost, hence firms by investing in the risky technology and fully financing with debt attain a higher value, since $A > B$ and there is no cost attached to debt financing. But if all firms only invest in the risky technology we have shown in the previous section there can be no equilibrium where $v_{t+1} = q_{t+1}$.

Having shown that $v_{t+1} > q_{t+1}$, the market clearing condition in the liquidation market implies that at least a positive fraction of firms invest in the risky technology. Hence at a competitive equilibrium two possible cases arise. The first one is a situation where all firms invest in the risky technology. The equilibrium is then the same as in the previous section. More precisely, a competitive equilibrium $\left\{ (c^*_t, k^*_t, z^*_t, l^*_t, q^*_t, v^*_t, r^*_t) \right\}_{t=0}^{\infty}$ according to Definition 5 is also an equilibrium when consumption good producers also face a choice
between a risky and a safe technology provided the equilibrium values satisfy the following condition, for all $t$,\[ v_t^* \geq \frac{1}{1 + r_t} v_{t+1}^* \left( \frac{B}{q_{t+1}^*} + \bar{\theta} \right), \] (30)that is, no producer can gain at these prices by switching from the risky to the safe technology.

The second case arises when (30) is violated, in which case the competitive equilibrium is different and entails a positive fraction $(1 - \ell_t^{**}) \in (0, 1)$ of firms using the safe technology. In this case, the equilibrium conditions need to be partly modified, in particular the liquidation market clearing condition, which becomes\[ q_t^{**} \int_{z_t^{**}} \theta_t dF = \ell_t^{**} A (1 - F(z_t^{**})) + (1 - \ell_t^{**}) B, \] (31)to reflect the fact that the buyers of capital goods now include the solvent firms investing in the risky technology and all the firms investing in the safe technology, as well as the good market clearing condition,\[ A\ell_t^{**} k_t^{**} + B (1 - \ell_t^{**}) k_t^{**} = c_t^{**} + I_t^{**}, \] (32)to reflect the differing productivities of the two technologies. In addition, condition (29), requiring that firms must be indifferent between the safe and risky technologies, must also hold.

We investigate in what follows the welfare properties of these equilibria. We show in particular that the availability of an alternative, safe technology, which allows firms to avoid the default risk, generates an additional source of inefficiency.

**Proposition 11** There exists a unique value of $B$, denoted by $\bar{B} > 0$, such that if $B \leq \bar{B}$ we have $\ell^{**} = 1$ in any steady-state equilibrium $(c^{**}, k^{**}, z^{**}, I^{**}, q^{**}, v^{**}, r^{**}, \ell^{**})$. By contrast, for some $\varepsilon > 0$ and any $B \in (\bar{B}, \bar{B} + \varepsilon)$, $\ell^{**} < 1$ and the consumption level $c^{**}$ is lower than in the equilibrium with $\ell^{**} = 1$.

In what follows we focus again our attention on the case where (19) holds, that is consumers are risk neutral. Hence, the critical value of $B$, denoted by $\bar{B}$, is given by\[ \bar{B} = \frac{q^* (1 - \delta \bar{\theta})}{\delta}, \]where $q^*$ is the price of liquidated capital at a steady-state equilibrium of the economy with no safe technology. At this steady-state equilibrium price, (30) holds with equality when $B = \bar{B}$, hence firms are indifferent between using the safe and risky technologies. At $\bar{B} + dB > \bar{B}$, (30) no longer holds, the steady-state equilibrium involves a positive fraction of firms $1 - \ell^{**} > 0$ adopting the safe technology and a higher steady-state equilibrium value of $q$,

\[ q^{**} = \frac{\delta (\bar{B} + dB)}{1 - \delta \bar{\theta}}, \] (33)
We show in the proof of the proposition in the Appendix that equilibrium welfare is lower at a new steady-state equilibrium than at the original one. Since the original allocation, with all firms investing in the risky technology, clearly remains feasible, this shows that the equilibrium indeed exhibits an inefficient technology choice, with excessive investment in the safe technology, as claimed.

The intuition for the result is as follows. At the competitive equilibrium with \( B = B + dB \), a positive fraction of firms adopt the safe technology, hence the liquidity available is higher and \( q \) lower. However, as we show in the proof, the market value of the firm, \( v \), decreases, which implies that the steady-state investment and capital stock both decrease. This drop in \( v \) reflects the fact that an inefficient technology is used, thus reducing the amount of available resources (a real cost in this case).

It is interesting to note that as \( B \) is increased further and, in particular, as \( B \) approaches \( A \), the safe technology is in the limit as productive as the risky one and consumption and the value of the firm both approach their first best steady state levels. Thus, the inefficiency vanishes in the limit. This shows that the relationship between the equilibrium value of \( v \) and \( B \) is non monotonic: if we keep increasing \( B \), eventually \( v \) must increase as well. The availability of a safe technology that can provide liquidity reduces the cost for firms of issuing debt and hence reduces the cost borne by firms to issue equity. As \( B \) keeps increasing, this effect ends up prevailing over the cost associated with the use of an inefficient technology.

7 Conclusion

We have analyzed the firms’ capital structure choice in a dynamic general equilibrium economy with incomplete markets. Firms face a standard trade-off between the exemption of interest payments on debt from the corporate income tax and the risk of costly default. The cost of default arises from the fact that if a firm defaults on its debt, it may be forced to liquidate its assets in a fire sale. Fire sales are endogenous and arise from the illiquidity of the capital market where the firm’s assets are sold. When the corporate income tax rate is zero, there are no fire sales, the firm’s capital structure is indeterminate, and the equilibrium is efficient. When the tax rate is positive, we show that fire sales are an essential part of the equilibrium, the optimal capital structure is uniquely determined in equilibrium and firms’ investment is below the first-best level. Moreover, the amount of debt chosen by the firm is constrained inefficient: increasing the ratio of debt to equity (more precisely, the breakeven level) will increase the level of investment and the welfare of the representative consumer. We also show that the introduction of a safe asset, which allows firms to make arbitrage profits in the capital markets, may actually reduce welfare. Although the arbitrage activity increases the liquidity of the market and raises the price of liquidated assets, it also reduces the return on capital and, hence, may lower the incentive to invest.

These findings highlight the subtle asymmetry between the corporate income tax and the risk of fire sales in default. Whereas the revenues from the corporate income tax are paid as lump sum transfers to consumers and leave the corporate sector, the capital gains from fire sales remain within the corporate sector and offset the capital losses. The introduction of a
safe asset operates through a different mechanism, by diverting the capital gains from fire sales to the firms choosing the safe, but less productive asset.

It is through such pecuniary externalities, concerning the price of firms’ liquidated assets, that the choice of capital structure affects welfare when markets are incomplete. These pecuniary externalities are the key to understanding the impact of capital structure on welfare in general equilibrium.

Although the model we have studied deals with firms that produce goods, the results are suggestive for the current debate about the funding and capital structure of financial institutions in the wake of the financial crisis. A similar exercise for financial institutions would seem to be an important topic for future research.

References


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Proofs

Proof of Proposition 1  From the strict concavity of $\varphi$ and the gradient inequality, it follows that, for any $k < \hat{k}$,

\[
\varphi(Ak) \leq \varphi(A\hat{k}) + \varphi'(A\hat{k}) A(k - \hat{k}) \\
= (1 - \bar{\theta}) \hat{k} + \varphi'(A\hat{k}) A(k - \hat{k}) \\
< (1 - \bar{\theta}) \hat{k}.
\]

Hence

\[
\varphi(Ak) + \bar{\theta}k < (1 - \bar{\theta}) \hat{k} + \bar{\theta}k < \hat{k}.
\]

For any $k > \hat{k}$,

\[
\varphi(Ak) \leq \varphi(A\hat{k}) + \varphi'(A\hat{k}) A(k - \hat{k}) \\
< (1 - \bar{\theta}) \hat{k} + (1 - \bar{\theta})(k - \hat{k}) \\
= (1 - \bar{\theta}) k,
\]

where the second inequality follows from the assumptions made on $\varphi(\cdot)$, implying the existence of a unique solution for $\hat{k}$. Thus,

\[
k_t > \hat{k} \implies k_{t+1} < k_t
\]

and

\[
k_t < \hat{k} \implies k_{t+1} < \hat{k}.
\]

Proof of Proposition 2  At an optimal steady state the multipliers $\{(\lambda_t^*, \mu_t^*)\}_{t=0}^\infty$ satisfy

\[
\lambda_t^* = \delta^t u'(c^*) = \delta^t \lambda_0^*,
\]

and hence

\[
\mu_t^* = \frac{\lambda_t^*}{\varphi'(I^*)} = \frac{\delta^t \lambda_0^*}{\lambda_0^*/\mu_0^*} = \delta^t \mu_0^*,
\]

for every $t$. The first-order conditions for the steady-state optimum can then be written as

\[
\begin{align*}
    u'(c^*) &= \lambda_0^*, \\
    \delta \lambda_0^* A + \delta \mu_0^* \bar{\theta} &= \mu_0^*, \\
    \mu_0^* \varphi'(I^*) &= \lambda_0^*.
\end{align*}
\]

Conditions (35) and (36) can be rewritten as

\[
\begin{align*}
    \frac{\delta A}{1 - \delta \theta} &= \frac{\mu_0^*}{\lambda_0^*} = \frac{1}{\varphi'(I^*)}.
\end{align*}
\]
The feasibility conditions become
\[ c^* + I^* = Ak^* \]
and
\[ k^* = \bar{\theta}k^* + \varphi(I^*). \]
Thus,
\[ k^* = \frac{\varphi(I^*)}{1 - \bar{\theta}}, \]
where \( I^* \) is determined by (37).

**Proof of Proposition 4**  The firm’s choice problem (12) can be rewritten as follows:

\[
v_t = \max_{z_{t+1}} \frac{1}{1 + r_t} \left\{ \int_0^{z_{t+1}} (A + q_{t+1} \theta_{t+1}) f(\theta_{t+1}) d\theta_{t+1} + \int_{z_{t+1}}^1 \left( v_{t+1} \left( \frac{A}{q_{t+1}} + \theta_{t+1} \right) - \tau v_{t+1} (\theta_{t+1} - z_{t+1}) \right) f(\theta_{t+1}) d\theta_{t+1} \right\}.
\]

The derivative of the expression on the right hand side with respect to \( z_{t+1} \) is easily calculated to be

\[
\frac{1}{1 + r_t} \left\{ (A + q_{t+1} z_{t+1}) f(\theta_{t+1}) - v_{t+1} \left( \frac{A}{q_{t+1}} + z_{t+1} \right) f(\theta_{t+1}) + \right.
\]

\[
(\theta_{t+1} - z_{t+1}) f(\theta_{t+1}) + \tau v_{t+1} (1 - F(z_{t+1})) \right\}
\]

\[
= \frac{1}{1 + r_t} \left\{ \left( 1 - \frac{v_{t+1}}{q_{t+1}} \right)^A f(\theta_{t+1}) + \left( 1 - \frac{v_{t+1}}{q_{t+1}} \right) q_{t+1} z_{t+1} f(\theta_{t+1}) + \tau v_{t+1} (1 - F(z_{t+1})) \right\}.
\]

The first-order condition for an interior solution of the firm’s problem requires this expression to equal zero, a condition which can be written as

\[
\left( \frac{v_{t+1}}{q_{t+1}} - 1 \right) (A + q_{t+1} z_{t+1}) f(\theta_{t+1}) = \tau v_{t+1} (1 - F(z_{t+1})),
\]

or

\[
\left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) (A + q_{t+1} z_{t+1}) \frac{f(z_{t+1})}{1 - F(z_{t+1})} = \tau.
\]

Since all terms on the left hand side are positive, the solution to this equation, if it exists, is unique if all these terms are increasing in \( z_{t+1} \). Obviously, \( A + q_{t+1} z_{t+1} \) is increasing in \( z_{t+1} \), and so is \( \frac{f(z_{t+1})}{1 - F(z_{t+1})} \) under the assumption of an increasing hazard rate.

From the above expression of the derivative we also see that a corner solution with \( z_{t+1} = 0 \) obtains when \( \left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) A f(0) > \tau \). In contrast, it is easy to verify that a corner solution with \( z_{t+1} = 1 \) never exists. By the continuity of the objective function in \( z_{t+1} \), a solution always exists, so it follows that an interior solution exists when \( \left( 1 - \frac{q_{t+1}}{v_{t+1}} \right) A f(0) < \tau \).
Market clearing in the securities market  The markets for debt and equity clear at any \( t \) if the amount of wealth the households want to carry forward into the next period is equal to the value of debt and equity issued by firms in that period. The latter is equal to the market value of depreciated capital, \( v_t \theta k_t \), plus the value of newly produced capital goods, \( v_t \varphi (I_t) \). To find the consumer’s savings, we need first to find the value of the consumer’s wealth in sub-period \( C \) of date \( t \). This is equal to the \textit{sum} of the profits from the capital good sector, the proceeds from the liquidation of firms which defaulted in this period, and the value of the firms that did not default in the period \textit{minus} the corporation tax and the lump sum transfer from the government. The corporation tax and the transfer cancel in equilibrium and can be ignored. Hence, the consumer’s wealth, \( w_t \), is given by

\[
w_t = v_t \varphi (I_t) - I_t + A \int_0^{z_t} k_t f (\theta_t) d\theta_t + q_t \int_0^{z_t} \theta_t k_t f (\theta_t) d\theta_t + v_t \bar{\theta} k_t + A \int_{z_t}^1 k_t f (\theta_t) d\theta_t - q_t \int_0^{z_t} \theta_t k_t f (\theta_t) d\theta_t = v_t \varphi (I_t) - I_t + A k_t + v_t \bar{\theta} k_t.
\]

Therefore, the securities market clears at date \( t \) if

\[
w_t - c_t = v_t \varphi (I_t) - I_t + A k_t + v_t \bar{\theta} k_t = v_t (\bar{\theta} k_t + \varphi (I_t))
\]

or

\[
c_t + I_t = A k_t.
\]

So market clearing in the goods market implies market clearing in the securities markets.

Proof of Proposition 7  Equation (16) comes directly from Condition 4 of the definition of competitive equilibrium, applied to a steady state. Equation (18) is simply the first-order condition from Condition 2 of the definition of competitive equilibrium.

The law of motion of the value of the firm can be written as

\[
v^* = \delta \left\{ \int_0^{z^*} (A + q^* \theta) dF + \int_{z^*}^1 \left( \frac{v^*}{q^*} (A + q^* \theta) - \tau v^*(\theta - z^*) \right) dF \right\}
\]

\[
= \delta \left\{ \int_0^{z^*} (A + v^* \theta - (v^* - q^*) \theta) dF + \int_{z^*}^1 \left( A + \left( \frac{v^*}{q^*} - 1 \right) A + v^* \theta - \tau v^*(\theta - z^*) \right) dF \right\}
\]

\[
= \delta \left\{ \int_0^{z^*} \left( A + v^* \theta - \left( \frac{v^*}{q^*} - 1 \right) q^* \theta \right) dF + \int_{z^*}^1 \left( A + v^* \theta + \left( \frac{v^*}{q^*} - 1 \right) A - \tau v^*(\theta - z^*) \right) dF \right\}
\]

\[
= \delta \left\{ A + v^* \theta - \int_{z^*}^1 \tau v^*(\theta - z^*) dF \right\}
\]

where in the last step we used (16) to simplify the expression. Solving the last equation we obtained for \( v \), we get:

\[
v^* \left( 1 - \delta \theta + \tau \int_{z^*}^1 (\theta - z^*) dF \right) = \delta A
\]
or

\[ v^* = \frac{\delta A}{1 - \delta\theta + \tau \int_{z^*}^{1} (\theta - z^*) dF} \]

which is equation (17).

Now the value of \( v^* = v(z^*) \) given by equation (17) is an increasing function of \( z^* \) and the value of \( q^* = q(z^*) \) given by (16) is a decreasing function of \( z^* \). Writing the first-order condition (18) as

\[
\left(1 - \frac{q(z^*)}{v(z^*)}\right) \left(\frac{A}{q(z^*)} + z^*\right) \frac{f(z^*)}{1 - F(z^*)} = \tau,
\]

it is clear from inspection that the terms on the left hand side are increasing in \( z^* \), so there exists at most one steady state.

To see that there exists a solution to (38), note that as \( z^* \to 0 \), \( q(z^*) \to \infty \) and \( v(z^*) \to \frac{\delta A}{1 - \delta\theta + \tau \int_{z^*}^{1} (\theta - z^*) dF} \), so for some finite value \( z^* > 0 \), \( q(z^*) = v(z^*) \) and the left hand side of (38) equals zero. Next, consider what happens as \( z^* \to 1 \) and note that \( q(z^*) \to 0 \) and \( v(z^*) \to \frac{\delta A}{1 - \delta\theta} > 0 \), so the left hand side of (38) is positive. Thus, by continuity, there exists a value of \( 0 < z^* < 1 \) satisfying (38).

**Proof of Proposition 8** Consider first the effect of a change in \( \tau \). From equation (16) it is clear that \( q^* = q(z^*) \) is independent of \( \tau \) whereas equation (17) shows that \( v^* = v(z^*, \tau) \) is decreasing in \( \tau \). Then the first-order condition (38) can be rewritten as

\[
\left(1 - \frac{q(z^*)}{v(z^*, \tau)}\right) \left(\frac{A}{q(z^*)} + z^*\right) \frac{f(z^*)}{1 - F(z^*)} = \tau.
\]

An increase in \( \tau \) increases the right hand side and, by decreasing \( v(z^*, \tau) \), it decreases the left hand side. Thus, to satisfy the first-order condition, the left hand side must be increased and that requires an increase in \( z^* \). Thus, an increase in \( \tau \) increases \( z^* \) and, hence, reduces \( q^* = q(z^*) \). Since \( v(z^*, \tau) \) is increasing in \( z^* \) and decreasing in \( \tau \), the net effect on \( v^* \) (and hence the effect on \( I^* \) and \( k^* \)) is uncertain. What we can say, from equation (17), is that \( v^* \) (and hence \( I^* \) and \( k^* \)) will increase if the tax revenue \( \tau \int_{z^*}^{1} (\theta - z^*) dF \) declines as a result of the increase in \( \tau \).

Now consider the impact of an increase in \( \delta \). Again, \( q^* = q(z^*) \) is independent of \( \delta \), whereas \( v^* = v(z^*, \delta) \) is increasing in \( \delta \) according to (17). Rewriting the first-order condition (18) as follows

\[
\left(1 - \frac{q(z^*)}{v(z^*, \delta)}\right) \left(\frac{A}{q(z^*)} + z^*\right) \frac{f(z^*)}{1 - F(z^*)} = \tau,
\]

it is clear that an increase in \( \delta \) will increase \( v(z^*, \delta) \) and hence increase the left hand side. To satisfy the first-order condition, the left hand side must be decreased, which requires a decrease in \( z^* \). From (16), \( q^* \) must increase as a result of the decrease in \( z^* \). The decrease in \( z^* \) in turn will lead to a decrease in \( v \), but the overall effect on \( v \), since in this case the term on the left hand side of (18) must stay constant for (18) to hold, is that \( v \) increases (actually more than \( q \)). Hence \( I^* \) and \( k^* \) also increase.
Proof of Proposition 9  At the unique steady-state value, \( z = z^* \), the derivative of the term on the left hand side of (23), \( v'(z^*) \), is negative and strictly smaller than the derivative of the term on the right hand side. Denoting the term on the right hand side by \( \varphi(z_{t+1}) \), where \( \varphi(z) \) is defined by

\[
\varphi(z) = \delta \left[ A + v(z) \tilde{\theta} - \tau v(z) \int_z^1 (\theta - z) dF \right],
\]

we have

\[
\varphi'(z^*) = \delta v'(z^*) \tilde{\theta} - \delta \tau v'(z^*) \int_z^1 (\theta - z) dF + \delta \tau v(z^*) (1 - F(z^*))
\]

\[
> \delta v'(z^*),
\]

since the second and third terms on the right hand side are positive. Then the fact that \( v'(z^*) \) is negative and \( 0 < \delta < 1 \) implies that \( \varphi'(z^*) > v'(z^*) \) as claimed. Since the steady state is unique, this proves that

\[
v(z) \geq \varphi(z) \quad \text{as} \quad z \leq z^*,
\]

for all \( 0 < z < 1 \).

We show next that \( \varphi'(z) < 0 \), for all \( 0 < z < 1 \). This is equivalent to

\[
- \frac{v'}{v} > \frac{\tau (1 - F(z))}{\theta - \tau \int_z^1 (\theta - z) dF}.
\]

(39)

Differentiating (21) we get

\[
\frac{v'}{v} = \frac{d}{dz} \left( \frac{\tau}{\left( \frac{A}{q} + z \right) \frac{f}{1-F}} \right) \frac{v}{q} + \left( \frac{q'}{q} \right).
\]

Also, from (20) we get

\[
q' = -Af \int_0^z \theta dF - A(1 - F)zf \left( \frac{f}{1-F} \right)^2.
\]

Since \( -\frac{q'}{q} > 0 \), a sufficient condition for (39) to hold is that

\[
- \frac{d}{dz} \left( \frac{\tau}{\left( \frac{A}{q} + z \right) \frac{f}{1-F}} \right) \frac{v}{q} = - \frac{v\tau}{q} \left[ \left( \frac{A}{q} q' - 1 \right) \left( \frac{f}{1-F} \right) - \left( \frac{A}{q} + z \right) \frac{d}{dz} \left( \frac{f}{1-F} \right) \right] \geq \frac{\tau (1 - F)}{\theta - \tau \int_z^1 (\theta - z) dF}.
\]

Recall that the hazard rate \( f/(1 - F) \) is assumed to be increasing. Hence the above inequality holds if

\[
\frac{v}{q} \left( \frac{1 - \frac{A}{q} q'}{\left( \frac{A}{q} + z \right)^2 \left( \frac{f}{1-F} \right)^2} \right) \geq \frac{(1 - F)}{\theta - \tau \int_z^1 (\theta - z) dF}.
\]

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Substituting the expression for \( q' \) derived above, this inequality can be rewritten as follows

\[
\frac{v}{q} \left( \frac{1 + A \frac{Af'_0}{q^2} \frac{\theta - \theta^*}{(\theta - z)^2}}{\frac{\theta - \tau^*}{\theta^*}} \right) > f \quad \frac{\theta - \tau^*}{\theta^*} \int_z^1 (\theta - z) dF,
\]

or, using (20) to substitute for \( q' \),

\[
\frac{v}{q} \left( \frac{1 + \theta^* (\theta - F) z}{(1-F)^2} \right) > \frac{1}{\theta - \tau^*} \int_z^1 (\theta - z) dF.
\]

Note that the term on the left hand side can be rewritten as

\[
\frac{v}{q} \left( \frac{(1-F)^2/f}{(1-F)^2} \right) + \frac{1}{\theta^* \theta dF + z(1-F)} > \frac{1}{\theta^* \theta dF + z(1-F)}
\]

where the inequality sign follows from the fact that \( v/q > 1 \). Hence (39) holds if

\[
\tilde{v} - \tau^* \int_z^1 (\theta - z) dF > \int_0^z \theta dF + z(1-F),
\]

or

\[
\tilde{v} - \int_0^z \theta dF - \tau^* \int_z^1 \theta dF = \int_z^1 \theta dF(1-\tau) > z(1-F)(1-\tau),
\]

always satisfied. This completes the proof that \( \varphi' (z) < 0 \), for all \( 0 < z < 1 \).

Denoting, as usual, the solution of (20) by \( q(z) \), we note that \( q(z) \to \infty \) as \( z \to 0 \) and \( q(z) \to 0 \) as \( z \to 1 \). Since the first-order condition (21) implies that \( v_t > q_{t+1} \), we have \( v(z) \to \infty \) as \( z \to 0 \). And since \( A/q(z) \to \infty \) as \( z \to 1 \), we must have \( v(z) \to 0 \) as \( z \to 1 \). Then \( v(z) \to \infty \) (resp. 0) as \( z \to 0 \) (resp. 1), whereas \( \varphi'(z) \) behaves like \( \delta [A + (1-\tau) \varphi'(z)] \) as \( z \to 0 \), that is, \( \varphi'(z) \to \infty \) as \( z \to 0 \), and \( \varphi'(z) \to \delta A \) as \( z \to 1 \).

Any sequence \( \{z_t\} \) satisfying the difference equation (21) that does not begin at \( z^* \) will diverge either to 0 or 1. If \( z_t \to 1 \), then within a finite number of steps \( v(z_t) < \delta A < \varphi(z) \) for any \( z \), so there does not exist a continuation value \( z_{t+1} \) that satisfies \( v(z) = \varphi(z_{t+1}) \). If \( z_t \to 0 \), on the other hand, then \( v_t(z_t) \to \infty \), which implies that \( I_t \to \infty \) and \( k_t \to \infty \), violating the boundedness property established in Proposition 1. Thus, no divergent sequence corresponds to an equilibrium and the only possible equilibrium sequence is \( z_t = z^* \) for all \( t \).

**Proof of Proposition 10** To see this, suppose to the contrary that at some date \( t \) a firm with one unit of capital at its disposal devotes a fraction \( \ell \) of it to the risky technology and the remaining fraction \( 1 - \ell \) to the safe technology. As usual, we define the break even point \( z_{t+1} \) for a debt with nominal value \( d_{t+1} \) as:

\[
\ell A + (1-\ell) B + q_{t+1} (\ell z_{t+1} + (1-\ell) \tilde{v}) = d_{t+1}.
\]
Then the expected value of the firm at date $t + 1$ is given by
\[
\int_0^{z_{t+1}} \left( \ell A + (1 - \ell) B + q_{t+1} \left( \ell \theta_{t+1} + (1 - \ell) \bar{\theta} \right) \right) dF + \int_{z_{t+1}}^1 \left[ \frac{v_{t+1}}{q_{t+1}} \left( \ell A + (1 - \ell) B + q_{t+1} \left( \ell \theta_{t+1} + (1 - \ell) \bar{\theta} \right) - \tau v_{t+1} \ell \left( \theta_{t+1} - z_{t+1} \right) \right] dF,
\]
since the tax base is
\[
\frac{v_{t+1}}{q_{t+1}} \left[ \ell A + (1 - \ell) B + q_{t+1} \left( \ell \theta_{t+1} + (1 - \ell) \bar{\theta} \right) - d_{t+1} \right] = \frac{v_{t+1}}{q_{t+1}} \left[ \ell A + (1 - \ell) B + q_{t+1} \left( \ell \theta_{t+1} + (1 - \ell) \bar{\theta} \right) \right] - v_{t+1} \ell \left( \theta_{t+1} - z_{t+1} \right).
\]

We show below that the firm can achieve a higher value by splitting into two separate entities, of size respectively $\ell$ and $1 - \ell$, the first one investing fully in the risky technology and the second one investing fully in the safe one. The nominal value of the debt in the second entity is set at $(1 - \ell) B + q_{t+1} (1 - \ell) \bar{\theta} = d_{t+1}$, while the one in the first entity is $\ell A + q_{t+1} \ell z_{t+1} = d_{t+1}$, that is the break even point is kept at $z_{t+1}$. The sum of the value of these two entities is then
\[
\ell \left[ \int_0^{z_{t+1}} \left( A + q_{t+1} \theta_{t+1} \right) dF + \int_{z_{t+1}}^1 \left( \frac{v_{t+1}}{q_{t+1}} \left( A + q_{t+1} \theta_{t+1} \right) - \tau v_{t+1} \left( \theta_{t+1} - z_{t+1} \right) \right) dF \right] +
\]
\[
(1 - \ell) \left[ \frac{v_{t+1}}{q_{t+1}} (B + q_{t+1} \bar{\theta}) \right]
\]
which is clearly strictly greater than the value of the combined firm above, as long as $v_{t+1} > q_{t+1}$. Moreover, the firm can also achieve a higher value by investing all the capital at its disposal in the risky technology, if the first term in square brackets is larger than the second one, and otherwise in the safe technology.

**Proof of Proposition 11** When $B = \bar{B}$ the steady state equilibrium is the same as in the previous sections, characterized in Proposition 7. Hence the equation determining the value of the firm is still given by (as in condition 2):
\[
v^* = \delta \left\{ \int_0^{z^{**}} (A + q^* \theta) dF + \int_{z^{**}}^1 \left( \frac{v^*}{q^*} (A + q^* \theta) - \tau v^* (\theta - z^*) \right) dF \right\}
\]
The change in the equilibrium value of $v$ when $B$ is increased to $\bar{B} + dB$ is obtained by differentiating this equation with respect to $B$ and evaluating the derivative at $B = \bar{B}$:
\[
\frac{dv}{dB} = \delta \left\{ \left( \int_0^{z^{**}} \theta dF \right) \frac{dq}{dB} + \left( \frac{1}{q^*} \int_{z^{**}}^1 (A + q^* \theta) dF \right) \frac{dv}{dB} - \left( \frac{v^*}{q^2} \int_{z^{**}}^1 A dF \right) \frac{dq}{dB} - \left( \tau \int_{z^{**}}^1 (\theta - z) dF \right) \frac{dv}{dB} \right\}.
\]
Rearranging, we get
\[
1 - \frac{\delta}{q^*} \int_{z^{*}}^{1} (A + q^* \theta) \, dF + \tau \int_{z^{*}}^{1} (\theta - z) \, dF \frac{dv}{dB} = \delta \left( \int_{0}^{z^*} \theta dF - \frac{v^*}{q^*} \int_{z^{*}}^{1} AdF \right) \frac{dq}{dB}.
\]

Now, using the market-clearing condition (16), we see that
\[
\frac{\delta}{q^*} \int_{z^{*}}^{1} (A + q^* \theta) \, dF = \frac{\delta}{q^*} \left( A (1 - F (z^*)) + \int_{z^*}^{1} q^* \theta dF \right)
= \frac{\delta}{q^*} \left( q^* \int_{0}^{z^*} \theta dF + q^* \int_{z^*}^{1} \theta dF \right)
= \delta \theta < 1.
\]

So,
\[
1 - \frac{\delta}{q^*} \int_{z^{*}}^{1} (A + q^* \theta) \, dF + \tau \int_{z^{*}}^{1} (\theta - z) \, dF = 1 - \delta \theta + \tau \int_{z^{*}}^{1} (\theta - z) \, dF
> 1 - \delta \theta > 0.
\]

Similarly, again using (16),
\[
\int_{0}^{z^*} \theta dF - \frac{v^*}{q^*} \int_{z^{*}}^{1} AdF = \int_{0}^{z^*} \theta dF - \frac{v^* A (1 - F (z^*))}{q^*}
< \int_{0}^{z^*} \theta dF - \int_{0}^{z^*} \theta dF = 0
\]

From these two inequalities, it follows that \(\frac{dv}{dB}\) and \(\frac{dq}{dB}\) have opposite signs. Since \(\frac{dv}{dB} > 0\) follows from (33) in the text, we have proved that \(\frac{dv}{dB} < 0\).

The change in the steady-state equilibrium consumption level is then obtained by differentiating (32) with respect to \(B\) and evaluating the derivative at \(B = \bar{B}\):
\[
dc^{**} = Adk^{**} - dI^{**} + (A - B)k^* d\ell^{**},
\]

since \(\ell^* = 1\). The profit maximization condition \(v^* \phi' (I^*) = 1\) implies, as already shown in the previous section, that a reduction in \(v^{**}\) reduces \(I^{**}\), and the law of motion \(k^{**} = \varphi (I^{**}) + \theta k^{**}\) implies that a reduction in \(I^{**}\) reduces \(k^{**}\):
\[
dk^{**} = \frac{\phi' (I^*)}{1 - \theta} dI^{**}
\]
Also, \( d\ell^* \leq 0 \) since \( \ell^* = 1 \) at the equilibrium associated with \( B = \bar{B} \). Then inspection of (41) yields

\[
dc^{**} < Adk^{**} - dI^{**} \\
= \left( \frac{A\varphi'(I^*)}{1 - \bar{\theta}} - 1 \right) dI^{**} \\
= \left( \frac{A}{\nu^* (1 - \bar{\theta})} - 1 \right) dI^{**},
\]

so a sufficient condition for \( dc^{**} < 0 \) is \( \nu^* (1 - \bar{\theta}) < A \). But it is clear from (40) that

\[
\nu^* \leq \delta A \left\{ 1 + \delta \bar{\theta} + (\delta \bar{\theta})^2 + \cdots (\delta \bar{\theta})^k + \cdots \right\} \\
= \frac{\delta A}{1 - \delta \bar{\theta}} < \frac{A}{1 - \bar{\theta}}.
\]

This completes the proof of the proposition.